## **GEFRAN**

# **PMA12**

# SELF-SUPPORTING LINEAR POSITION TRANSDUCER WITH MAGNETIC PULLING



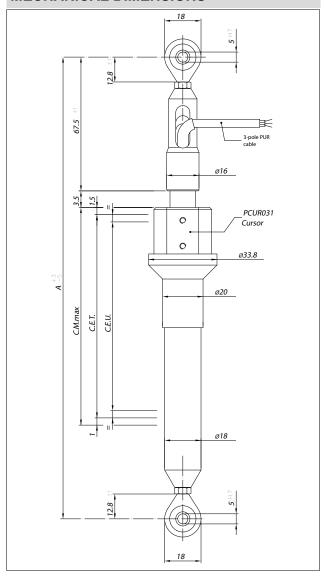
#### Principal characteristics

- The PMA-12 transducer, a development of the PME series, is designed for installation with self-aligning joints.
- The IP67 protection level makes the PMA-12 highly suitable for humid and wet environments and in temporary immersion (CEI EN 60529).
- Available only with cable output.
- Ideal for applications on metalworking and ceramics machines, as well as on earth-moving machines and utility vehicles. Recommended in all cases where the angle of the drive axle changes constantly.

## **TECHNICAL DATA**

Useful electical stroke (C.E.U.	) 50 to 1000mm
Independent linearity	see table
(within C.E.U.)	
Resolution	Infinite
Repeatability	≤ 0,08 mm
Hysteresis	≤ 0,25mm
Electrical connection	PMA12 F 3-pole shielded cable 1m
Protection level	IP67 (CEI EN 60529)
Life	> 25x106 m strokes, or
	> 100x10 <sup>6</sup> operations, whichever
	is less
Displacement speed	≤ 5 m/s
Max. acceleration	≤ 10m/s² displacement
Shock test DIN IEC68T2-27	50g, 11ms single stroke
Vibraziotions DIN IEC68T2-6	12g, 102000Hz
Cursor dragging force	≤ 0.5 N
Displacement sensitivity	da 0.05 a 0.1 mm
(no hysteresis)	
Tracking error	See table
Tolerance on resistance	±20%
Recommended cursor	< 0,1 µA
current	
Maximum cursor current in	
case of bad performances	10mA
·	
Maximum applicable voltage	See table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C	See table
(0W at 120°C)	
Thermal coefficient	-200 +200 ppm/°C typical
of resistance	
Actual Temperature Coefficient	≤ 5 ppm/°C typical
of the output voltage	
Working temperature	-30+100°C
Storage temperature	-50+120°C
Material for transducer	Anodised aluminium, PSU
case	
Material for cursor magnets	POM
Mounting	Self-aligning joints with adjustable
	distance between centres

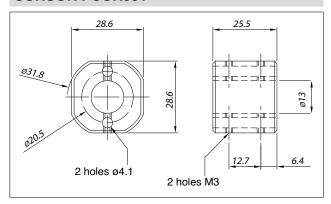
#### **MECHANICAL DIMENSIONS**



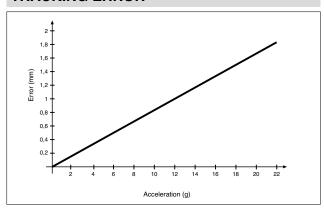
Important: all data shown in the catalog for linearity values and temperature coefficients are valid when the sensor is used as voltage divider with maximum current of  $lc \cdot 0.1 \mu A$  in the circuit.

ELECTRICAL / MECHANICAL DATA																						
MODEL		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	
Useful electrical stroke (U.E.S.) + 1 / -0	mm		Model																			
Theoretical electrical stroke (T.E.S.) ± 1	mm		U.E.S. + 1																			
Resistance (on T.E.S.)	kΩ		5						10						20							
Independent linearity (within U.E.S.)	±%	0	0,1						0,05													
Dissipation at 40°C (0W at 120°C)	W	1	2	2 3																		
Max. applicable voltage	٧	40	40 60																			
Mechanical stroke MC	mm		U.E.S. + 5																			
Joints distance minimum (A) +3 / -5	mm		U.E.S. + 158																			

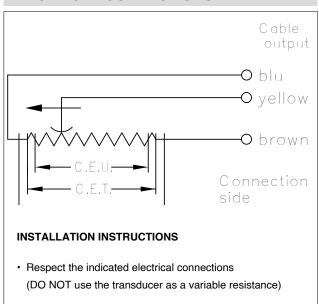
#### **CURSOR PCUR031**



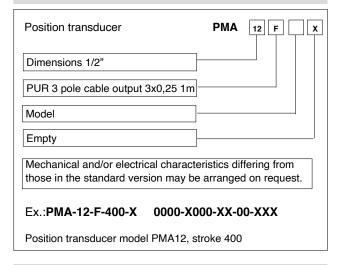
#### TRACKING ERROR



#### **ELECTRICAL CONNECTIONS**

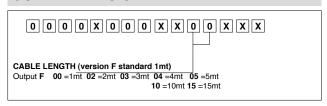


#### **ORDER CODE**



 When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

## **CODE EXTENSION**



GEFRAN spa reserved the right to make aesthetic or functional changes at any time and without notice.